

In the Claims:

- 1 **1.** (original) A method for assisting the driver of a vehicle
2 (10) when performing a driving maneuver, a reference
3 trajectory (16) corresponding to the driving maneuver being
4 determined, along which the vehicle (19) is to be moved,
5 and the steering wheel position to be set in each case and
6 controlling the vehicle (10) along the reference trajectory
7 (16, 19) being indicated to the driver during the driving
8 maneuver, characterized in that, in the event of a steering
9 angle deviation (d_{LW}) between the actual steering angle
10 (δ_{act}) actually set by the driver and the desired steering
11 angle (δ_{des}) corresponding to the requested steering wheel
12 position, the vehicle longitudinal speed (v) is influenced
13 independently of the driver.
- 1 **2.** (original) The method as claimed in claim 1, characterized
2 in that the influence on the vehicle speed is dependent on
3 the magnitude of the steering angle deviation (d_{LW}).

Claims 3 to 14 (canceled).

[REMARKS FOLLOW ON NEXT PAGE]